

# Towards continuous representations of Thompson groups $T_k$

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# Conformal nets

## Question (Jones 2014)

Does each subfactor planar algebra give rise to a conformal field theory?

A **conformal net** consists of (i) a Hilbert space  $\mathcal{H}$ , (ii) a *von Neumann algebra*  $\mathcal{A}(I)$  on  $\mathcal{H}$  for each open interval  $I \subset S^1$ , (iii) a continuous unitary representation  $U$  of  $\text{Diff}_+(S^1)$  on  $\mathcal{H}$ . Subject to:

Isotony:  $\mathcal{A}(I) \subseteq \mathcal{A}(J)$  if  $I \subseteq J$

Locality:  $[\mathcal{A}(I), \mathcal{A}(J)] = 0$  if  $I \cap J = \emptyset$

Covariance:  $U(\alpha)\mathcal{A}(I)U(\alpha)^* = \mathcal{A}(\alpha(I))$   $\alpha \in \text{Diff}_+(S^1)$

Positivity:  $\text{Spec}(U(\rho)) \subset \mathbb{R}^+$   $\rho \in \text{Rot}(S^1)$

# Planar algebras

## Definition

An (unshaded) **planar algebra**  $P$  is a collection of vector spaces  $(P_n)_{n \in \mathbb{N}_0}$ , together with the action of planar tangles as multilinear maps e.g.

$$T = \text{[Diagram of a planar tangle } T \text{ with 3 inputs and 1 output]} , \quad P_T : P_2 \times P_4 \times P_6 \rightarrow P_8$$

such that this action is compatible with the composition of tangles.

For example:

$$P_T(\text{[Diagram 1]}, \text{[Diagram 2]}, \text{[Diagram 3]}) = \text{[Diagram 4]} = \text{[Diagram 5]} = \text{[Diagram 6]}$$

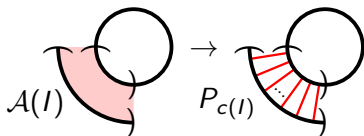
*Subfactor planar algebras* have an inner product on each  $(P_n)_{n \in \mathbb{N}_0}$ .

# Semicontinuous models

*Semicontinuous models* are lattice regularisations of conformal nets

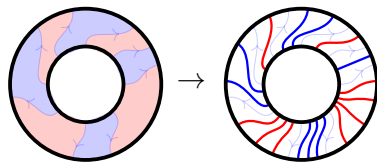
$$(\mathcal{H}, \mathcal{A}(I)) \rightarrow (\mathcal{P}, \mathcal{P})$$

*Planar algebra*



$$\text{Diff}_+(S^1) \rightarrow T_k$$

*Thompson group*



# No-go?

The idea: semicontinuous models  $\rightarrow$  conformal nets

The issue: **Covariance:**  $U(\alpha)\mathcal{A}(I)U(\alpha)^* = \mathcal{A}(\alpha(I)) \quad \alpha \in \text{Diff}_+(S^1)$   
Reps. of  $T_k$  are projective and unitary, but not continuous!

The dream: Develop sufficient conditions that endow reps. of  $T_k$  with the property of continuity

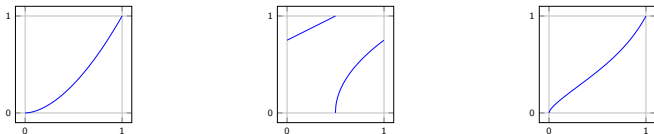
# Outline

- 1 Thompson groups  $T_k$
- 2 Representations of  $T_k$
- 3 Continuity conditions
- 4 Outlook

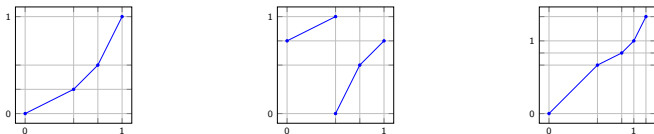
Thompson groups  $T_k$

# $\text{Diff}_+(S^1)$ and $T_k$

Elements of  $\text{Diff}_+(S^1)$  can be conveniently expressed as functions:



Elements of  $T_k$  can be viewed as 'discretisations' of  $\text{Diff}_+(S^1)$  elements:



with break-points at finitely many  $k$ -adic rational coordinates.

## Theorem (Zhuang 2007)

For every  $f \in \text{Diff}_+(S^1)$  there exists  $g \in T_k$ , and  $\epsilon > 0$  such that

$$\sup_{x \in S^1} |g(x) - f(x)| < \epsilon.$$

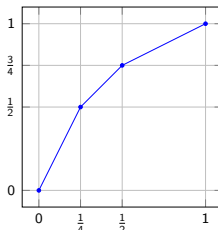


# Tree diagrams

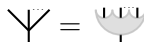
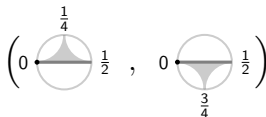
## Proposition (Brown 1987)

Elements of  $T_k$  can be expressed as pairs of annular  $k$ -trees.

For  $k = 2$  we present the example:



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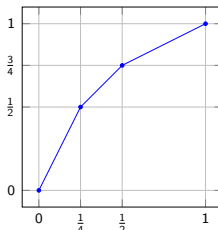


# Tree diagrams

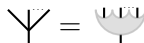
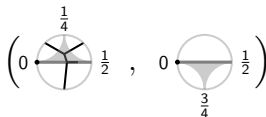
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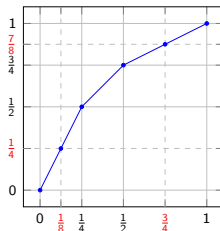
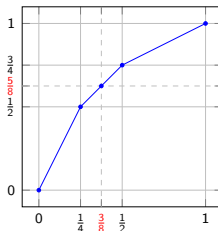
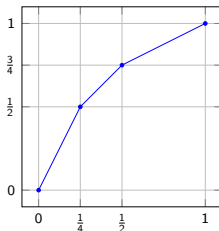


# Tree diagrams

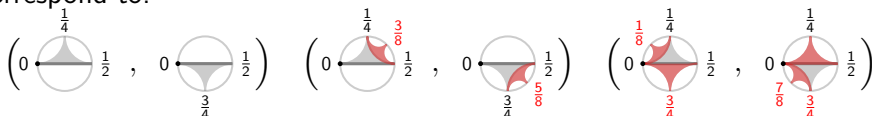
## Proposition (Brown 1987)

Elements of  $T_k$  can be expressed as pairs of annular  $k$ -trees.

Many pairs of annular  $k$ -trees give rise to the same element of  $T_k$ :



Correspond to:



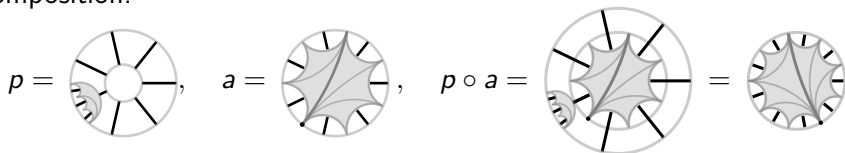
where the highlighted branches correspond to unnecessary divisions.

# Forest categories

Denote by  $A_{\mathfrak{F}_k}$  the category of annular  $k$ -forests:

- $\text{Obj}_{A_{\mathfrak{F}_k}} = \mathbb{N}$
- $\text{Mor}_{A_{\mathfrak{F}_k}}(m, n)$  are annular  $k$ -forests with  $m$  roots and  $n$  leaves

Composition:



where  $p \in \text{Mor}_{A_{\mathfrak{F}_2}}(7, 9)$  and  $a \in \text{Mor}_{A_{\mathfrak{F}_2}}(1, 7)$ . Define

$$\mathcal{D} := \bigcup_{n \in \mathbb{N}} \text{Mor}_{A_{\mathfrak{F}_k}}(1, n)$$

as the set of all annular  $k$ -trees, and denote  $\ell(f) := \text{target}(f)$  for  $f \in \mathcal{D}$ .

# Fraction notation

Define  $\sim$  on pairs of annular  $k$ -trees as  $(a, y) \sim (b, z)$  if and only if there exist  $r, s \in \text{Mor}_{A\mathfrak{F}_k}$  such that  $(r \circ a, r \circ y) = (s \circ b, s \circ z)$

## Proposition (Brown 1987)

Two pairs of annular  $k$ -trees  $(a, y)$  and  $(b, z)$  correspond to the same element in  $T_k$  if and only if  $(a, y) \sim (b, z)$ .

Denote by  $[(c, x)] \equiv \frac{c}{x}$  the equiv. class  $(c, x)$

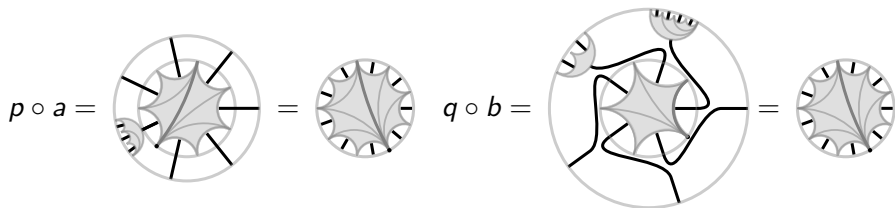
$$\frac{p \circ c}{p \circ x} = \frac{c}{x},$$

where we interpret  $p \in \text{Mor}_{A\mathfrak{F}_k}$  as being 'cancelled' in the fraction. Taking the trees from a previous slide:

$$\frac{\text{Tree 1}}{\text{Tree 2}} = \frac{\text{Tree 3}}{\text{Tree 4}} = \frac{\text{Tree 5}}{\text{Tree 6}}$$

# Composition via fractions

Any  $a, b \in \mathcal{D}$  admit  $p, q \in \text{Mor}_{A_{\mathfrak{S}_k}}$  such that  $p \circ a = q \circ b$ , called a *stabilisation*:



Composition of functions can be expressed as the product of fractions

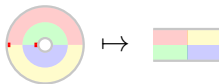
$$G \circ H = \frac{a}{b} \frac{c}{d} = \frac{\cancel{q \circ a}}{q \circ b} \frac{p \circ c}{\cancel{p \circ d}} = \frac{p \circ c}{q \circ b}, \quad \text{where } q \circ a = p \circ d,$$

where  $G \circ H$  has the domain of  $H$  and the range of  $G$ .

## Representations of $T_k$

# Preliminaries

For convenience we will use the cutting convention:



Denote by  $\text{Hilb}$  the category of Hilbert spaces:

- $\text{Obj}_{\text{Hilb}}$  are Hilbert spaces  $V_n$  for each  $n \in \mathbb{N}$
- $\text{Mor}_{\text{Hilb}}(V_m, V_n)$  are linear maps

where the inner product on each  $V_n$  can be expressed diagrammatically as:

$$\langle x, y \rangle_n = \begin{array}{c} \boxed{x^*} \\ | \quad | \quad | \quad \dots \quad | \\ \boxed{y} \end{array}, \quad \begin{array}{c} \overbrace{\quad \quad \quad}^n \\ | \quad | \quad | \quad \dots \quad | \\ \boxed{x} \end{array}, \quad \begin{array}{c} \overbrace{\quad \quad \quad}^n \\ | \quad | \quad | \quad \dots \quad | \\ \boxed{y} \end{array} \in V_n$$



# Jones' action

Define the functor  $\Phi : A_{\mathfrak{F}_k} \rightarrow \text{Hilb}$

- $\Phi_0(n) = V_n$  for all  $n \in \mathbb{N}$
- $\Phi_1^R(p) \in \text{Mor}_{\text{Hilb}}(V_m, V_n)$  for all  $p \in \text{Mor}_{A_{\mathfrak{F}_k}}(m, n)$

$$p = \text{[diagram]}, \quad \Phi_1^R(p) = \text{[diagram]}, \quad \text{[diagram]} \in P_{k+1}$$

Construct the set  $A_\Phi$  such that:

	$T_k$	$A_\Phi$
Elements	$\frac{f}{g} = \frac{p \circ f}{p \circ g}$	$\frac{f}{\textcolor{red}{g}} = \frac{p \circ f}{\Phi_1^R(p)(\textcolor{red}{g})}$
Action of $T_k$	$\frac{f_1}{g_1} \frac{f_2}{g_2} = \frac{q \circ f_2}{p \circ g_1}$	$\frac{f_1}{\textcolor{red}{x}_1} \frac{f_2}{g_2} = \frac{\cancel{p \circ f_1}}{\Phi_1^R(p)(\textcolor{red}{x}_1)} \frac{q \circ f_2}{\cancel{q \circ g_2}} = \frac{q \circ f_2}{\Phi_1^R(p)(\textcolor{red}{x}_1)}$

where  $\textcolor{red}{x} \in V_{\ell(f)}$ ,  $\textcolor{red}{x}_1 \in V_{\ell(f_1)}$ . Inducing Hilbert space  $\mathfrak{H}$  and a representation

$$\pi_R : T_k \rightarrow \text{End}(A_\Phi).$$

## Continuity conditions

# Continuous representations

## Definition

A representation  $\pi$  is *continuous* if each sequence  $(f_n)_{n \in \mathbb{N}} \subset T_k$  satisfies

$$\lim_{n \rightarrow \infty} \|f_n - \text{id}\| = 0, \quad \lim_{n \rightarrow \infty} \langle \xi, \pi(f_n)(\eta) \rangle = \langle \xi, \eta \rangle, \quad \forall \xi, \eta \in \mathfrak{H}.$$

Denote by  $\text{Rot}_k$  the rotation subgroup of  $T_k$ , generated by:

$$\rho_s : S^1 \rightarrow S^1, \quad x \mapsto x + s \pmod{1},$$

where  $s$  is a  $k$ -adic rational. Matrix elements can be expressed as:

$$\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{k^r}})(\frac{i}{y}) \rangle = \text{diagram} = \langle x, \Omega_{k^r} y \rangle_{k^r}, \quad \Omega_n := \underbrace{\text{diagram}}_n$$

where  $x, y \in V_{k^r}$ .

The matrix elements can be expressed in terms of a *transfer operator*:

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{k^r+s}}) \left( \frac{i}{y} \right) \right\rangle = \left\langle x, T_{kr}(\mathfrak{R}^s(v)) y \right\rangle_{kr}, \quad v := \text{diagram}$$

where

$$T_n(a) = \underbrace{\text{diagram with } n \text{ nodes}}_n, \quad \mathfrak{R}(a) = \text{diagram with 3 nodes}$$

To illustrate, we present a small example where  $x, y \in V_3$ :

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{3^3}}) \left( \frac{i}{y} \right) \right\rangle = \text{diagram with 3 columns of nodes}$$

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where

$$T_n(a) = \underbrace{\text{diagram with } n \text{ nodes}}_n, \quad \mathfrak{R}(a) = \text{diagram with one node}$$

To illustrate, we present a small example where  $x, y \in V_3$ :

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$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{k^r+s}}) \left( \frac{i}{y} \right) \right\rangle = \left\langle x, T_{k^r}(\Re^s(v)) y \right\rangle_{k^r}, \quad v := \text{diagram}$$

where

$$T_n(a) = \text{diagram with } n \text{ nodes } a \text{ in a row} \quad \Re(a) = \text{diamond diagram with node } a \text{ in the center}$$

To illustrate, we present a small example where  $x, y \in V_3$ :

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{3^3}}) \left( \frac{i}{y} \right) \right\rangle = \text{diagram with 3 diamond blocks connected horizontally, top boundary } x^*, \text{ bottom boundary } y$$

The matrix elements can be expressed in terms of a *transfer operator*:

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{kr+s}}) \left( \frac{i}{y} \right) \right\rangle = \left\langle x, T_{kr}(\mathfrak{R}^s(v)) y \right\rangle_{kr}, \quad v := \text{diagram}$$

where

$$T_n(a) = \text{diagram with } n \text{ nodes } a \text{ in a row}, \quad \mathfrak{R}(a) = \text{diagram with } a \text{ in a hexagon}$$

To illustrate, we present a small example where  $x, y \in V_3$ :

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{3^3}}) \left( \frac{i}{y} \right) \right\rangle = \text{diagram with } x^* \text{ and } y \text{ connected by three nodes labeled } \mathfrak{R}^2(v)$$

The matrix elements can be expressed in terms of a *transfer operator*:

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{k^r+s}})(\frac{i}{y}) \right\rangle = \left\langle x, T_{k^r}(\mathfrak{R}^s(v))y \right\rangle_{k^r}, \quad v := \text{diagram}$$

where

$$T_n(a) = \text{diagram} \quad \mathfrak{R}(a) = \text{diagram}$$

To illustrate, we present a small example where  $x, y \in V_3$ :

$$\left\langle \frac{i}{x}, \pi_R(\varrho_{\frac{1}{3^3}})(\frac{i}{y}) \right\rangle = \left\langle x, T_3(\mathfrak{R}^2(v))y \right\rangle_3$$



# Continuity conditions

Applying:

$$\lim_{s \rightarrow \infty} \left\langle \frac{i}{X}, \pi_R(\varrho_{\frac{1}{kr+s}})(\frac{i}{y}) \right\rangle = \lim_{s \rightarrow \infty} \langle x, T_{kr}(\mathfrak{R}^s(v))y \rangle_{kr} \stackrel{(!)}{=} \langle x, y \rangle_{kr}$$

## Proposition

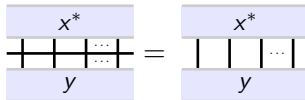
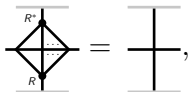
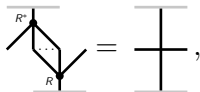
If there exists a  $w \in P_4$  such that

$$\mathfrak{R}(v) = w, \quad \mathfrak{R}(w) = w, \quad \langle x, T_{kr}(w)y \rangle_{kr} = \langle x, y \rangle_{kr} \quad (\star)$$

for all  $x, y \in V_{kr}$ , then

$$\lim_{s \rightarrow \infty} \left\langle \frac{i}{X}, \pi_R(\varrho_{\frac{1}{kr+s}})(\frac{i}{y}) \right\rangle = \langle x, y \rangle_{kr}.$$

A concrete realisation of  $(\star)$  is given by:



# Brauer algebra solution

The Brauer planar algebra  $(B_n)_{n \in 2\mathbb{N}_0}$  is generated by the action of planar tangles on the space  $B_4 = \text{span}(\{ \textcircled{\bullet} \textcircled{\bullet} , \textcircled{\cup} , \textcircled{\cap} \})$ , subject to:

$$\textcircled{\times} = \textcircled{\bullet} \textcircled{\bullet}$$

$$\textcircled{\mathcal{D}} = \delta \textcircled{\bullet}$$

$$\textcircled{\cap} = \textcircled{\cup}$$

Specialising  $k = 5$  and  $\delta = 1$  we have the solution  $\textcircled{\cup}_R = \textcircled{\cup}$

$$\textcircled{\cup}_{R^*} = \textcircled{\cup} = \textcircled{\cap},$$

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This solution can be generalised to  $k = 2n + 5$  for all  $n \in \mathbb{N}_0$

$$\textcircled{\cup}_R = \textcircled{\cup}_n,$$

$$\textcircled{\cup}_n \in P_{2n}.$$

## Theorem

For  $R \in P_{2n+5}$  above,  $\pi_R$  is a continuous unitary representation of  $\text{Rot}_{2n+5}$ .

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$$\begin{array}{c} R^* \\ \diagup \quad \diagdown \\ \text{---} \\ \diagdown \quad \diagup \\ R \end{array} = \textcircled{\cap}_R = \textcircled{\cup}_R = \text{---}$$

This solution can be generalised to  $k = 2n + 5$  for all  $n \in \mathbb{N}_0$

$$\textcircled{\cap}_R = \textcircled{\cup}_R, \quad \textcircled{\cap}_n \in P_{2n}.$$

## Theorem

For  $R \in P_{2n+5}$  above,  $\pi_R$  is a continuous unitary representation of  $\text{Rot}_{2n+5}$ .

## Outlook

# Outlook

## Summary:

- Semicontinuous models of conformal nets via planar algebras.
- Limited by the continuity of the representations of  $T_k$ .
- Developed sufficient conditions that imply continuity of representations of the rotation subgroup of  $T_k$ .

## Future work:

- Solve the continuity conditions for other types of planar algebras.
- Construct sufficient conditions that implies the continuity of representation of all  $T_k$
- Develop the limit that takes continuous representations of  $T_k$  to continuous representations of  $\text{Diff}_+(S^1)$ .

The end!